Tutorial: Ethical and Technical Challenges and Considerations of Robots and Systems

Session I: Ethical and technical perspectives



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2022 IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS-2022)



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Zoom receives backlash for emotion-detecting AI



By Ryan Daws | May 19, 2022 | TechForge Media Categories: Applications, Artificial Intelligence, Companies, Ethics & Society, Face Recognition, Privacy, Voice Recognition,

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Zoom has caused a stir following reports that it's developing an AI system for detecting emotions.

The system, first reported by Protocol, claims to scan users' faces and their speech to determine their emotions.

- Scan users' faces and their speech to determine their emotions.
- Zoom detailed the system more in a blog post last month (April 2022). The company says 'Zoom IQ' will be particularly useful for helping salespeople improve their pitches based on the emotions of call participants.

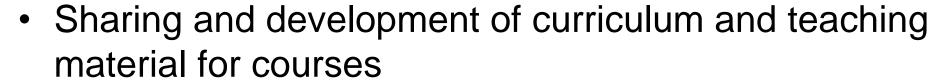
Tutorial Agenda – Ethical perspectives and technical challenges and opportunities with care robots

- 1. Introduction and motivation
- 2. Ethical challenges and perspectives
- 3. How to address ethical considerations in research including examples
- 4. Ethical considerations in own research at University of Oslo
- 5. Future opportunities in ethics-related research

Collaboration on Intelligent Machines Norway (COINMAC) ←→ US, Brazil and Japan







- Long term mobility stay (students)
- Intensive course/student workshop
- Workshop/conference org. activities
- New collaborations/guest lectures (can be in Canada, South-



Funding: INTPART 2017-2024



Korea, ++)







Why do we not want AI and robots?

- Privacy: Collects a lot of data that can be published or misused?
- Safety and security: Can harm us physically (and mentally)?

Society: Colder society?



Future jobs: Taking away our jobs?

Why AI and robots?



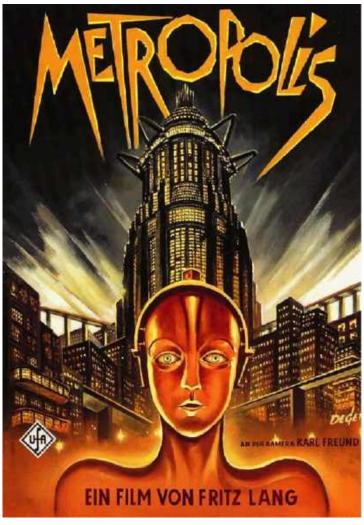
 We can do (mental and physical) work with less effort

Reduced manual routine work

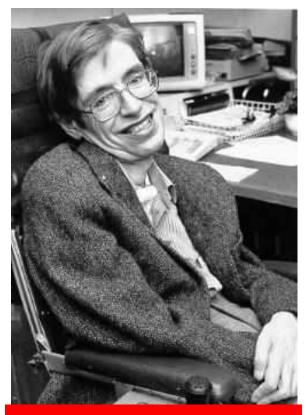
 Improve dignity by making us more independent of the help of others

Giving us better health and longer life

Is Terminator Coming Soon?



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"Humans, limited by slow biological evolution, couldn't compete and would be superseded by A.I."





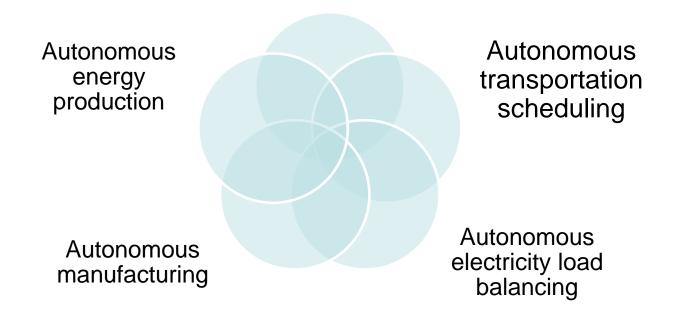
"I am in the camp that is concerned about super intelligence."

Ethical Risks of Developing AI Systems

- Jobs: People may become unemployed because of automation.?
- Jobs: We get too much free time.?
- Technology: Loosing human skills?
- **Technology:** Artificial intelligence can be used for destructive and unwanted tasks.?
- Technology: Successful KI can lead to the extinction of mankind?

Future Scenario with Autonomous Interacting Al Systems

Autonomous stock investment



Ethical Countermeasures

- Designers, procurers and users need to be aware of possible ethical challenges that should be considered
 - e.g. avoiding misuse and allowing for human inspection of the functionality
- The systems should themselves be able to do ethical decision making to reduce the risk of unwanted behavior
 - Decide when a human is to be contacted or the machine should stop



Machine Ethics: Moor 's four categories of ethical agency

- 1) Ethical Impact Agents: Any machine that can be evaluated for its ethical consequences.
- 2) Implicit Ethical Agents: Machines that are designed to avoid unethical outcomes.
- 3) Explicit Ethical Agents: Machines that can reason about ethics.
- 4) Full Ethical Agents: Machines that can make explicit moral judgments and justify them.

A. F. Winfield, K. Michael, J. Pitt and V. Evers, "Machine Ethics: The Design and Governance of Ethical AI and Autonomous Systems [Scanning the Issue]," in *Proceedings of the IEEE*, vol. 107, no. 3, pp. 509-517, March 2019, doi: 10.1109/JPROC.2019.2900622.

J. H. Moor, "The nature, importance, and [33] difficulty of machine ethics," *IEEE Intell. Syst.*, vol. 21, no. 4, pp. 18–21, Jul./Aug. 2006.

International Work on Ethics and Al

- IEEE Standards Association
 - Prioritizing Human Wellbeing with Artificial Intelligence and Autonomous Systems
- ISO/IEC JTC 1/SC 42 Artificial intelligence
 - Standardization in the area of Artificial Intelligence
- EU High-Level Expert Group on Artificial Intelligence
 - 52 experts on Artificial Intelligence, comprising representatives from academia, civil society, as well as industry.
 - support the implementation of the European strategy on Artificial Intelligence.
 - recommendations on future-related policy development and on ethical, legal and societal issues related to AI, including socio-economic challenges.

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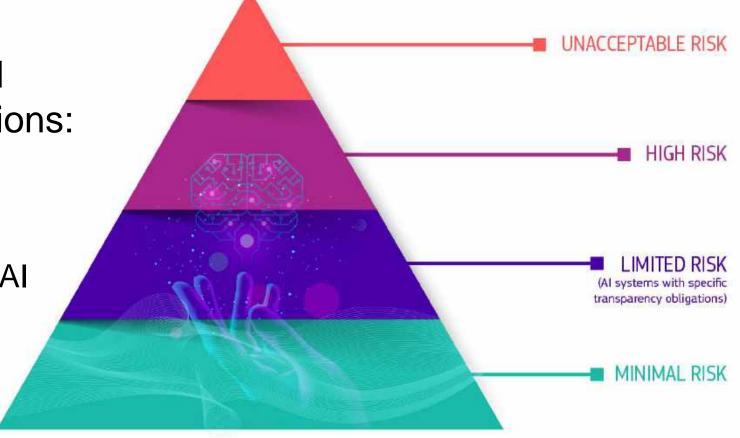


EU s risk-based approach to Al

European Commission
has proposed harmonised
rules regarding AI applications:

• EU Al Act Proposal:

- Prohibition of unacceptable Al practices
- Regulation of high-riskAl systems



Source:

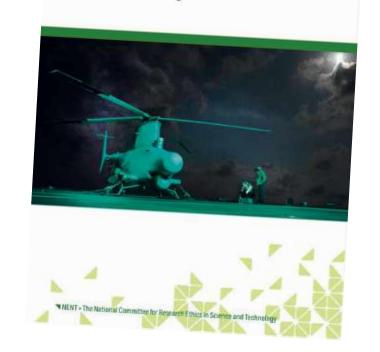


How to address ethical considerations in research: NENT AI Research Ethics Considerations Report

NENT – The National Committee for Research Ethics
in Science and Technology (Norway)

Statement on research ethics in artificial intelligence

- Input from relevant academic/research institutions involved in artificial intelligence research
- Review of international and national reports and guidelines
- Given by NENT in 2019 (Norwegian). An English translation published in October 2020.





Characteristics of AI – NENT AI report considerations

- 1. Al mimics, replaces and extends human intelligent action and human decision-making and assessment (four considerations)
- 2. Al has **numerous applications** (two considerations)
- 3. Al uses and generates big data (three considerations)



University of Oslo

Ethical considerations in own research at Univ of Oslo

University of Oslo, Norway







Robotics and Intelligent Systems (ROBIN)



Jim Tørresen Professor, Group leader



Mats Høvin Assoc. Prof.



Kyrre Glette Professor



Kai Olav Ellefsen Assoc. Prof.



Yngve Hafting Ass. Prof.



Vegard D Søyseth Principal Engineer

Adrian Bergflødt **Assistant Engineer**

Postdocs: Frank Veenstra (IFI)



Ulysse Côté-Allard (PIRC)



Diana Saplacan (VIROS)



Adjunct positions (20%):

Alexander Wold (assoc.prof.) Ole Jakob Elle (Prof.) Roar Skogstrøm (lecturer) Ståle Skogstad (assoc.prof.) Tønnes Nygaard (lecturer)

PhD students

(ROBIN main superv.):

Adel Baselizadeh **Benedikte Wallace (RITMO) Bjørn Ivar Teigen (DOMOS) Bjørn Thor Jonsson (RITMO) Emma H Stensby** Farzan M. Noori Ivar-Kristian Waarum (NGI) Julian Fuhrer (RITMO) **Katrine Nergård** Marieke van Otterdijk Mojtaba Karbasi (RITMO)

Mateusz Wasiluk (BioAl)

Shin Watanabe

Tom Frode Hansen (NGI)

Students: Bachelor ~200; Master: ~60 **Robotics and Intelligent Systems program**

Students hired on hourly basis: Magnus E. Seierstad

Visiting researchers

https://www.mn.uio.no/ifi/english/research/groups/robin



RITMO Centre of Excellence for Interdisciplinary Studies in Rhythm, Time and Motion grant 262762 (2017-2027)

- The center will study the perceptual, cognitive and acting mechanisms underlying our ability to experience rhythm and act rhythmically.
- Interdisciplinary collaboration between musicology, psychology, computer science and robotics.
- Machine learning and robotics to be applied

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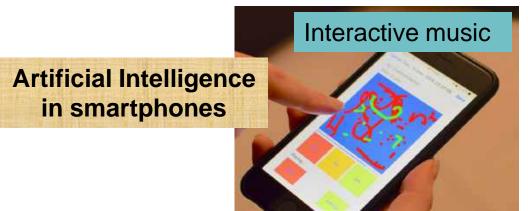




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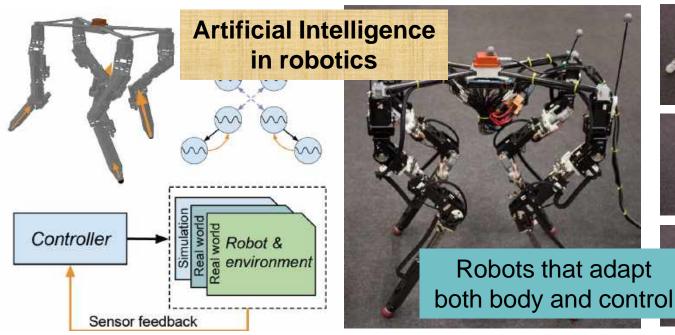
PAL TIAGo

Robotics and Intelligent Systems (ROBIN) research group















ROBIN Research Projects and Centre Funded by the Research Council of Norway

- INtroducing personalized TReatment Of Mental health problems using Adaptive Technology (INTROMAT, 2016-2021, LightHouse project)
- Multi-sensor Elderly Care Systems/Robots (MECS, 2015–2021, IKTPLUSS)
- Vulnerability in the Robot Society (VIROS, 2019-2023, IKTPLUSS)
- Predictive and Intuitive Robot Companion (PIRC, 2020-2025, IKTPLUSS)
- Centre of Excellence for Interdisciplinary Studies in Rhythm, Time and Motion (RITMO, 2017-2027, CoE)





MECS: Multi-sensor Elderly Care Systems

Research Council of Norway grant 247697 (2015–2021)

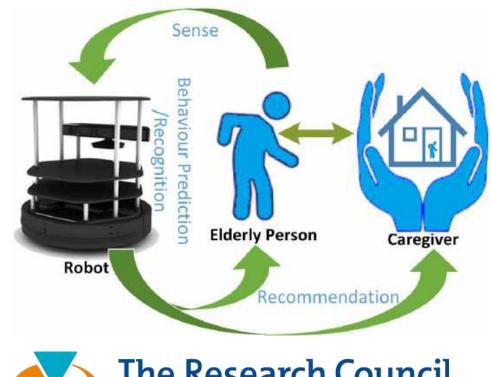
https://www.mn.uio.no/ifi/english/research/projects/mecs

Goal: Create and evaluate multimodal mobile human supportive systems that are able to sense, learn and predict future events.



Funding: FRINATEK
Research Council of Norway

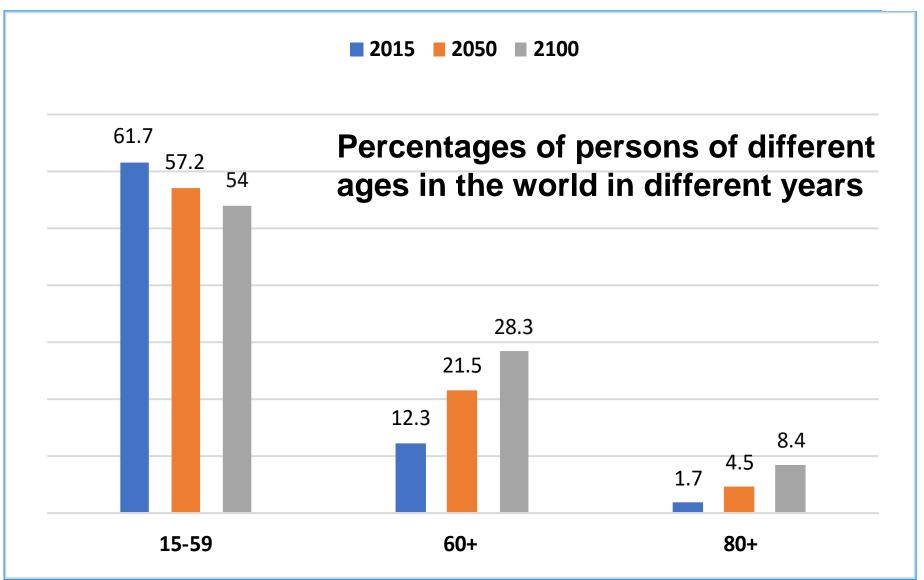
Web page: Google for "MECS IFI"





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United Nations (2015) World population ageing. United Nations, New York.

Robots and Older People

Would we like to be surrounded by robots rather than humans?

Robots and Older People

Would we like – with some help from robots – to be independent with regards to our key needs like personal care, eating and transportation?

Myself: Yes, but my preference would be impacted by the ease of use and performance and to some extent the look of the robot.

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MECS Research

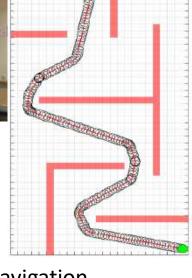
Diana Saplacan Rebekka Soma Trenton Schulz





User needs and preferences





Apply sensors that provides non/less-intrusive sensing



+ Master students

Robot sensing

Robot control

Navigation without a map









User Centered Design – Participatory Design

- involve real users in actual use contexts (home of older people)
- focus on behavior and satisfying the needs and desires of the users
- achieve improvements through iterative testing and improvement
- Oslo municipality elderly care facility: Kampen Omsorg +
- Vitalis home for elderly in Eindhoven in the Netherlands



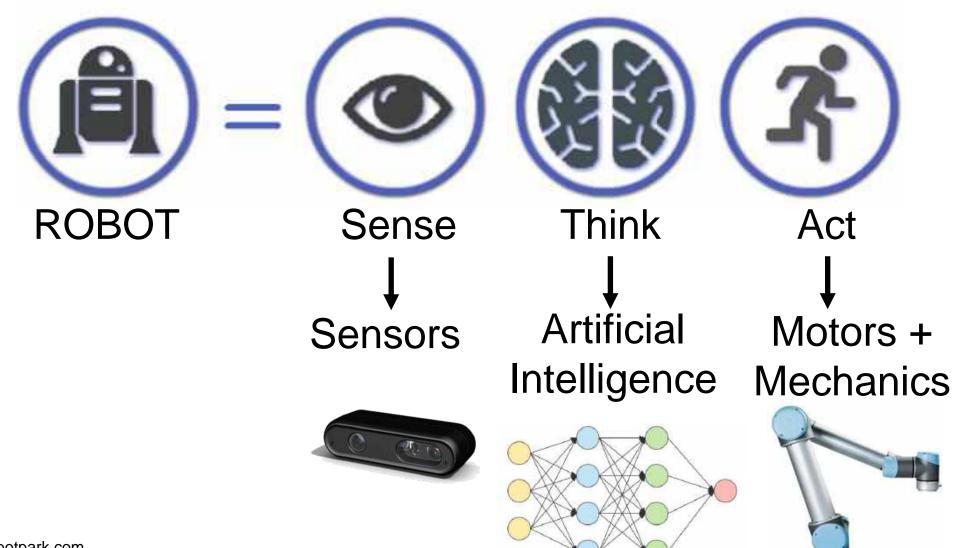
4. Potential lack of contact with other humans



Ethical Concerns:



3.Safety



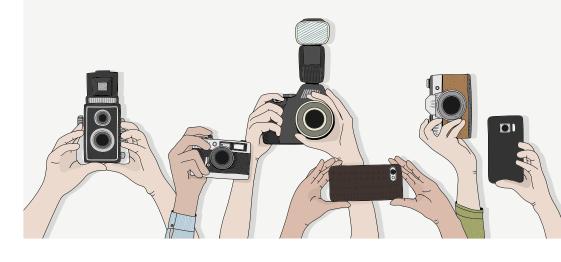


Ethical Concerns: 1. Privacy

- Challenge 1: Balance the privacy of the elderly against the needs for data collection for having an efficiently functioning elderly care systems.
- Challenge 2: Protection of sensitive data to avoid unwanted distribution and misuse of such data.
- Mitigation:
 - Sensor type: Use sensors collecting less privacy related information (person identifiable vs bio-signals/medical diagnostic)
 - -Sensor data processing: Process data locally rather than sending sensor data over Internet

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Privacy challenges / paradoxes





- How much data to collect: The more data that are used during research and development, the less data is needed when a system is to be applied.
- What kind of sensors: The more sensors, the more accurate and safer the robot will be.
- Consent: A personalised robot will act better and safer: the more you know about a friend, the more you tend to adapt to the person. (ref. web page cookie preferences will give easier use and more personalised web page view)



The MECS project has explored a number of novel non/less-intrusive sensors



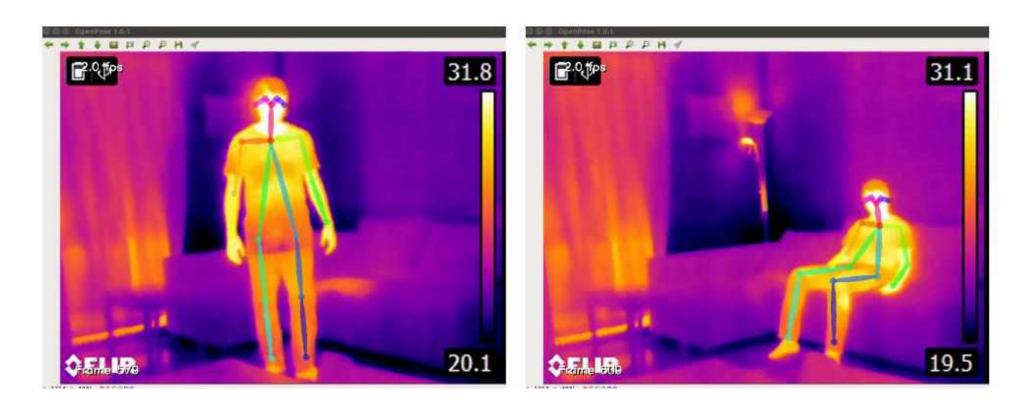


FLIR
Thermal
Camera



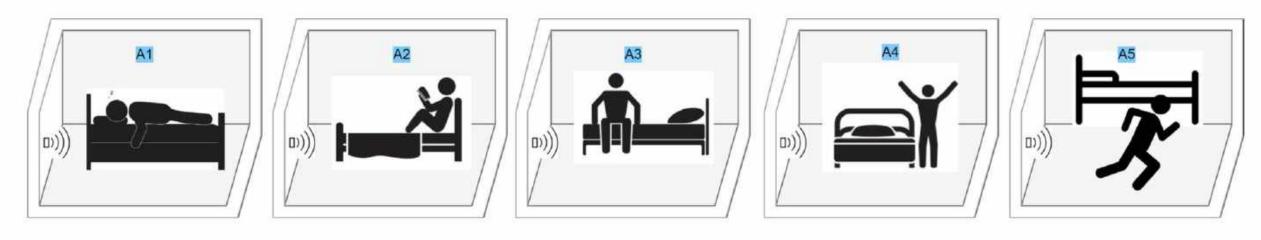


Non/less-Intrusive Sensing (thermal camera)



Md. Zia Uddin and Jim Torresen. A Deep Learning-Based Human Activity Recognition in Darkness, The 9th IEEE Colour and Visual Computing Symposium 2018 (CVCS 2018), Sept. 19-20, 2018

Ultra-Wideband (UWB) Radar-Based Activity Recognition



- LSTM-based activity recognition approach performed better than conventional approaches, with an accuracy of 99.6%.
- We applied 5-fold cross-validation to test our approach.

F. M. Noori, M. Z. Uddin and J. Torresen, "Ultra-Wideband Radar-Based Activity Recognition Using Deep Learning," in *IEEE Access*, vol. 9, pp. 138132-138143, 2021, doi: 10.1109/ACCESS.2021.3117667.



Ethical Concerns: 2. Security

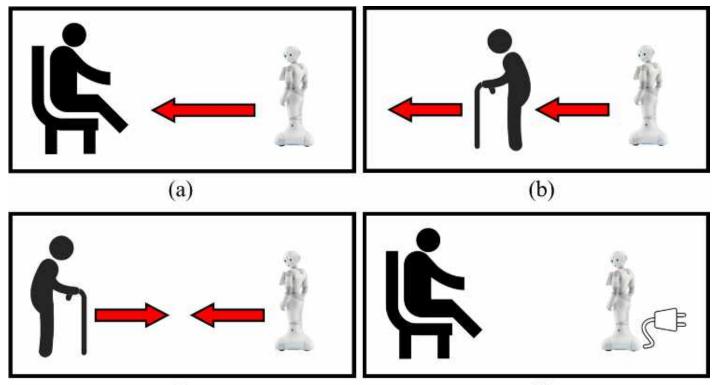
- Concern 1: Sensing possible theft and unwanted distribution of sensor data from a robot.
- Concern 2: Control risk of misbehaviour of the robot in similar ways as computers can be attacked with malware.
- Mitigation 1: Regular security measures with passwords and authentication
- Mitigation 2: Add an external user assessment module that can consider the current context (ref. ethical reasoning engine)

Ethical Concerns: 3. Safety

- Challenge: Robots getting physically much closer to humans than what we are used to. => Can hit us unintentionally or hurt us through un-authorized access
- Trade-off between robot size, performance and safety
- Mitigation:
 - Equip robots with soft material
 - Provide a self/user-aware adaptable system that can learn about the user staily activities and preferences
 - Explainable Al/transparent systems to be able to correct for unwanted or harming behavior

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User studies on robot and user encounters









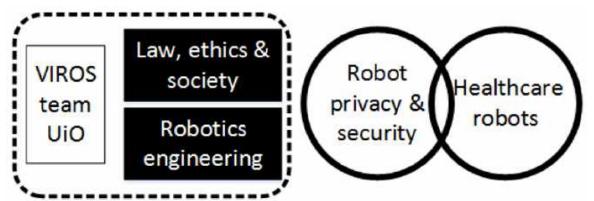
Khaksar, W.; Neggers, M.; Barakova, E.; and Torresen, J., "*Generation Differences in Perception of the Elderly Care Robot*," 2021 30th IEEE International Conference on Robot & Human Interactive Communication (RO-MAN), 2021, pp. 551-558

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VIROS: Vulnerability in the Robot Society (2019-2023)

Research Council of Norway grant 288285





Dep. of Private Law + Dep. of Informatics and other depts/partners

Goal:

Develop technology and proposals for regulatory measures to reduce vulnerabilities regarding robotics. Focus on privacy, security and safety, particularly in healthcare contexts.

Funding: IKTPLUSS, Research

Council of Norway





RITMO Centre of Excellence for Interdisciplinary Studies in Rhythm, Time and Motion grant 262762 (2017-2027)

- The center will study the perceptual, cognitive and acting mechanisms underlying our ability to experience rhythm and act rhythmically.
- Interdisciplinary collaboration between musicology, psychology, computer science and robotics.
- Machine learning and robotics to be applied

https://www.uio.no/ritmo/english







Human – Robot Interaction Slow Versus Safe Robot

- sloppy vs too slow
- must have general capabilities





Predictive and Intuitive Robot Companion (PIRC) (2020-2025)

Research Council of Norway grant 312333





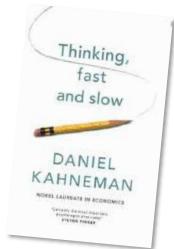


TIAGo mobile robot assistant



Goal: Build models that forecast future events and respond dynamically by psychology-inspired computing:

- Apply recent models of **human prediction** to perceptionaction loops of future intelligent robot companions.
- Include mechanisms for adaptive response time from quick and intuitive to slower and well-reasoned
- **Applications**: Physical rehabilitation and home care robot support for older people.



Funding: *IKTPLUSS,* Research Council of Norway



Future work and opportunities in ethics related research

privacy

- work with sensors collecting less privacy related data
- work on algorithms for local /edge computing (rather than cloud computing)

security

external user assessment module that can consider the current context

safety

- user-aware systems
- explainable Al/transparent systems to be able to correct for unwanted or harming behavior

potential lack of contact with other humans

- human dignity impacted by our independence
- politicians and society decide on the development as much as technology providers
- researchers can contribute to a **balanced public discussion**

We should focus as least as much on improved quality of life as reducing the cost by the technology being developed

Questions or Comments?

Make contact: jimtoer@ifi.uio.no

www.jimtoer.no



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